
pytest-cov

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CHAPTER 1

Overview

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This plugin produces coverage reports. Compared to just using `coverage run` this plugin does some extras:

- Subprocess support: you can fork or run stuff in a subprocess and will get covered without any fuss.
- Xdist support: you can use all of `pytest-xdist`'s features and still get coverage.
- Consistent `pytest` behavior. If you run `coverage run -m pytest` you will have slightly different `sys.path` (CWD will be in it, unlike when running `pytest`).

All features offered by the coverage package should work, either through `pytest-cov`'s command line options or through `coverage`'s config file.

- Free software: MIT license

1.1 Installation

Install with `pip`:

```
pip install pytest-cov
```

For distributed testing support install `pytest-xdist`:

```
pip install pytest-xdist
```

1.1.1 Upgrading from ancient pytest-cov

pytest-cov 2.0 is using a new `.pth` file (`pytest-cov.pth`). You may want to manually remove the older `init_cov_core.pth` from site-packages as it's not automatically removed.

1.1.2 Uninstalling

Uninstall with pip:

```
pip uninstall pytest-cov
```

Under certain scenarios a stray `.pth` file may be left around in site-packages.

- *pytest-cov 2.0* may leave a `pytest-cov.pth` if you installed without wheels (`easy_install`, `setup.py install` etc).
- *pytest-cov 1.8 or older* will leave a `init_cov_core.pth`.

1.2 Usage

```
pytest --cov=myproj tests/
```

Would produce a report like:

----- coverage: ... -----			
Name	Stmts	Miss	Cover

myproj/ <u>__init__</u>	2	0	100%
myproj/myproj	257	13	94%
myproj/feature4286	94	7	92%

TOTAL	353	20	94%

1.3 Documentation

<http://pytest-cov.rtd.org/>

1.4 Coverage Data File

The data file is erased at the beginning of testing to ensure clean data for each test run. If you need to combine the coverage of several test runs you can use the `--cov-append` option to append this coverage data to coverage data from previous test runs.

The data file is left at the end of testing so that it is possible to use normal coverage tools to examine it.

1.5 Limitations

For distributed testing the slaves must have the `pytest-cov` package installed. This is needed since the plugin must be registered through `setuptools` for `pytest` to start the plugin on the slave.

For subprocess measurement environment variables must make it from the main process to the subprocess. The python used by the subprocess must have pytest-cov installed. The subprocess must do normal site initialisation so that the environment variables can be detected and coverage started.

1.6 Acknowledgements

Whilst this plugin has been built fresh from the ground up it has been influenced by the work done on pytest-coverage (Ross Lawley, James Mills, Holger Krekel) and nose-cover (Jason Pellerin) which are other coverage plugins.

Ned Batchelder for coverage and its ability to combine the coverage results of parallel runs.

Holger Krekel for pytest with its distributed testing support.

Jason Pellerin for nose.

Michael Foord for unittest2.

No doubt others have contributed to these tools as well.

CHAPTER 2

Configuration

This plugin provides a clean minimal set of command line options that are added to pytest. For further control of coverage use a coverage config file.

For example if tests are contained within the directory tree being measured the tests may be excluded if desired by using a `.coveragerc` file with the `omit` option set:

```
pytest --cov-config=.coveragerc
       --cov=myproj
       myproj/tests/
```

Where the `.coveragerc` file contains file globs:

```
[run]
omit = tests/*
```

For full details refer to the [coverage config file](#) documentation.

Note that this plugin controls some options and setting the option in the config file will have no effect. These include specifying source to be measured (source option) and all data file handling (data_file and parallel options).

If you wish to always add `pytest-cov` with `pytest`, you can use `addopts` under `pytest` or `tool:pytest` section. For example:

```
[tool:pytest]
addopts = --cov=<project-name> --cov-report html
```

2.1 Caveats

A unfortunate consequence of `coverage.py`'s history is that `.coveragerc` is a magic name: it's the default file but it also means "try to also lookup coverage configuration in `tox.ini` or `setup.cfg`".

In practical terms this means that if you have your coverage configuration in `tox.ini` or `setup.cfg` it is paramount that you also use `--cov-config=tox.ini` or `--cov-config=setup.cfg`.

You might not be affected but it's unlikely that you won't ever use `chdir` in a test.

2.2 Reference

The complete list of command line options is:

--cov=PATH	Measure coverage for filesystem path. (multi-allowed)
--cov-report=type	Type of report to generate: term, term-missing, annotate, html, xml (multi-allowed). term, term-missing may be followed by ":skip-covered". annotate, html and xml may be followed by ":DEST" where DEST specifies the output location. Use <code>--cov-report=</code> to not generate any output.
--cov-config=path	Config file for coverage. Default: <code>.coveragerc</code>
--no-cov-on-fail	Do not report coverage if test run fails. Default: False
--no-cov	Disable coverage report completely (useful for debuggers). Default: False
--cov-fail-under=MIN	Fail if the total coverage is less than MIN.
--cov-append	Do not delete coverage but append to current. Default: False
--cov-branch	Enable branch coverage.

Reporting

It is possible to generate any combination of the reports for a single test run.

The available reports are terminal (with or without missing line numbers shown), HTML, XML and annotated source code.

The terminal report without line numbers (default):

```
pytest --cov-report term --cov=myproj tests/

----- coverage: platform linux2, python 2.6.4-final-0 -----
Name                               Stmts  Miss  Cover
-----
myproj/__init__                     2      0   100%
myproj/myproj                     257     13    94%
myproj/feature4286                  94      7    92%
-----
TOTAL                             353     20    94%
```

The terminal report with line numbers:

```
pytest --cov-report term-missing --cov=myproj tests/

----- coverage: platform linux2, python 2.6.4-final-0 -----
Name                               Stmts  Miss  Cover  Missing
-----
myproj/__init__                     2      0   100%
myproj/myproj                     257     13    94%  24-26, 99, 149, 233-236, 297-298, 369-370
myproj/feature4286                  94      7    92%  183-188, 197
-----
TOTAL                             353     20    94%
```

The terminal report with skip covered:

```
pytest --cov-report term:skip-covered --cov=myproj tests/

----- coverage: platform linux2, python 2.6.4-final-0 -----
↪-----
Name                               Stmts   Miss  Cover
-----
myproj/myproj                      257     13    94%
myproj/feature4286                 94       7    92%
-----
TOTAL                             353     20    94%

1 files skipped due to complete coverage.
```

You can use skip-covered with term-missing as well. e.g. `--cov-report term-missing:skip-covered`

These three report options output to files without showing anything on the terminal:

```
pytest --cov-report html
       --cov-report xml
       --cov-report annotate
       --cov=myproj tests/
```

The output location for each of these reports can be specified. The output location for the XML report is a file. Where as the output location for the HTML and annotated source code reports are directories:

```
pytest --cov-report html:cov_html
       --cov-report xml:cov.xml
       --cov-report annotate:cov_annotate
       --cov=myproj tests/
```

The final report option can also suppress printing to the terminal:

```
pytest --cov-report= --cov=myproj tests/
```

This mode can be especially useful on continuous integration servers, where a coverage file is needed for subsequent processing, but no local report needs to be viewed. For example, tests run on Travis-CI could produce a .coverage file for use with Coveralls.

Debuggers and PyCharm

(or other IDEs)

When it comes to TDD one obviously would like to debug tests. Debuggers in Python use mostly the `sys.settrace` function to gain access to context. Coverage uses the same technique to get access to the lines executed. Coverage does not play well with other tracers simultaneously running. This manifests itself in behaviour that PyCharm might not hit a breakpoint no matter what the user does. Since it is common practice to have coverage configuration in the `pytest.ini` file and `pytest` does not support `removeopts` or similar the `--no-cov` flag can disable coverage completely.

At the reporting part a warning message will show on screen:

```
Coverage disabled via --no-cov switch!
```


Distributed testing (xdist)

5.1 “load” mode

Distributed testing with dist mode set to load will report on the combined coverage of all slaves. The slaves may be spread out over any number of hosts and each slave may be located anywhere on the file system. Each slave will have its subprocesses measured.

Running distributed testing with dist mode set to load:

```
pytest --cov=myproj -n 2 tests/
```

Shows a terminal report:

```
----- coverage: platform linux2, python 2.6.4-final-0 -----
Name                               Stmts  Miss  Cover
-----
myproj/__init__                     2      0   100%
myproj/myproj                      257     13    94%
myproj/feature4286                  94      7    92%
-----
TOTAL                             353     20    94%
```

Again but spread over different hosts and different directories:

```
pytest --cov=myproj --dist load
      --tx ssh=memedough@host1//chdir=testenv1
      --tx ssh=memedough@host2//chdir=/tmp/testenv2//python=/tmp/env1/bin/python
      --rsyncdir myproj --rsyncdir tests --rsync examples
      tests/
```

Shows a terminal report:

```

----- coverage: platform linux2, python 2.6.4-final-0 -----
↩-----

```

Name	Stmts	Miss	Cover
-----	-----	-----	-----
myproj/___init___	2	0	100%
myproj/myproj	257	13	94%
myproj/feature4286	94	7	92%
-----	-----	-----	-----
TOTAL	353	20	94%

5.2 “each” mode

Distributed testing with dist mode set to each will report on the combined coverage of all slaves. Since each slave is running all tests this allows generating a combined coverage report for multiple environments.

Running distributed testing with dist mode set to each:

```

pytest --cov=myproj --dist each
      --tx popen//chdir=/tmp/testenv3//python=/usr/local/python27/bin/python
      --tx ssh=memedough@host2//chdir=/tmp/testenv4//python=/tmp/env2/bin/python
      --rsyncdir myproj --rsyncdir tests --rsync examples
      tests/

```

Shows a terminal report:

```

----- coverage -----
↩-----

```

		platform linux2, python 2.6.5-final-0	
		platform linux2, python 2.7.0-final-0	
Name	Stmts	Miss	Cover
-----	-----	-----	-----
myproj/___init___	2	0	100%
myproj/myproj	257	13	94%
myproj/feature4286	94	7	92%
-----	-----	-----	-----
TOTAL	353	20	94%

Subprocess support

Normally coverage writes the data via a pretty standard atexit handler. However, if the subprocess doesn't exit on its own then the atexit handler might not run. Why that happens is best left to the adventurous to discover by waddling through the Python bug tracker.

pytest-cov supports subprocesses and multiprocessing, and works around these atexit limitations. However, there are a few pitfalls that need to be explained.

6.1 If you use multiprocessing.Pool

pytest-cov automatically registers a multiprocessing finalizer. The finalizer will only run reliably if the pool is closed. Closing the pool basically signals the workers that there will be no more work, and they will eventually exit. Thus one also needs to call *join* on the pool.

If you use `multiprocessing.Pool.terminate` or the context manager API (`__exit__` will just call `terminate`) then the workers can get `SIGTERM` and then the finalizers won't run or complete in time. Thus you need to make sure your `multiprocessing.Pool` gets a nice and clean exit:

```
from multiprocessing import Pool

def f(x):
    return x*x

if __name__ == '__main__':
    p = Pool(5)
    try:
        print(p.map(f, [1, 2, 3]))
    finally:
        p.close()    # Marks the pool as closed.
        p.join()     # Waits for workers to exit.
```

If you must use the context manager API (e.g.: the pool is managed in third party code you can't change) then you can register a cleaning `SIGTERM` handler like so:

```
from multiprocessing import Pool

def f(x):
    return x*x

if __name__ == '__main__':
    try:
        from pytest_cov.embed import cleanup_on_sigterm
    except ImportError:
        pass
    else:
        cleanup_on_sigterm()

    with Pool(5) as p:
        print(p.map(f, [1, 2, 3]))
```

6.2 If you use multiprocessing.Process

There's similar issue when using the `Process` objects. Don't forget to use `.join()`:

```
from multiprocessing import Process

def f(name):
    print('hello', name)

if __name__ == '__main__':
    try:
        from pytest_cov.embed import cleanup_on_sigterm
    except ImportError:
        pass
    else:
        cleanup_on_sigterm()

    p = Process(target=f, args=('bob',))
    try:
        p.start()
    finally:
        p.join() # necessary so that the Process exists before the test suite exits_
↪ (thus coverage is collected)
```

6.3 If you got custom signal handling

pytest-cov 2.6 has a rudimentary `pytest_cov.embed.cleanup_on_sigterm` you can use to register a SIGTERM handler that flushes the coverage data.

pytest-cov 2.7 adds a `pytest_cov.embed.cleanup_on_signal` function and changes the implementation to be more robust: the handler will call the previous handler (if you had previously registered any), and is re-entrant (will defer extra signals if delivered while the handler runs).

For example, if you reload on SIGHUP you should have something like this:

```
import os
import signal
```

```
def restart_service(frame, signum):
    os.exec( ... ) # or whatever your custom signal would do
    signal.signal(signal.SIGHUP, restart_service)

try:
    from pytest_cov.embed import cleanup_on_signal
except ImportError:
    pass
else:
    cleanup_on_signal(signal.SIGHUP)
```

Note that both `cleanup_on_signal` and `cleanup_on_sigterm` will run the previous signal handler.

Alternatively you can do this:

```
import os
import signal

try:
    from pytest_cov.embed import cleanup
except ImportError:
    cleanup = None

def restart_service(frame, signum):
    if cleanup is not None:
        cleanup()

    os.exec( ... ) # or whatever your custom signal would do
    signal.signal(signal.SIGHUP, restart_service)
```

6.4 If you use Windows

On Windows you can register a handler for `SIGTERM` but it doesn't actually work. It will work if you `os.kill(os.getpid(), signal.SIGTERM)` (send `SIGTERM` to the current process) but for most intents and purposes that's completely useless.

Consequently this means that if you use multiprocessing you got no choice but to use the `close/join` pattern as described above. Using the context manager API or `terminate` won't work as it relies on `SIGTERM`.

However you can have a working handler for `SIGBREAK` (with some caveats):

```
import os
import signal

def shutdown(frame, signum):
    # your app's shutdown or whatever
    signal.signal(signal.SIGBREAK, shutdown)

try:
    from pytest_cov.embed import cleanup_on_signal
except ImportError:
    pass
else:
    cleanup_on_signal(signal.SIGBREAK)
```

The `caveats` being roughly:

- you need to deliver `signal.CTRL_BREAK_EVENT`
- it gets delivered to the whole process group, and that can have unforeseen consequences

CHAPTER 7

Tox

When using `tox` you can have ultra-compact configuration - you can have all of it in `tox.ini`:

```
[tox]
envlist = ...

[tool:pytest]
...

[coverage:paths]
...

[coverage:run]
...

[coverage:report]
..

[testenv]
commands = ...
```

An usual problem users have is that `pytest-cov` will erase the previous coverage data by default, thus if you run `tox` with multiple environments you'll get incomplete coverage at the end.

To prevent this problem you need to use `--cov-append`. It's still recommended to clean the previous coverage data to have consistent output. A `tox.ini` like this should be enough for sequential runs:

```
[tox]
envlist = clean,py27,py36,...

[testenv]
commands = pytest --cov --cov-append --cov-report=term-missing ...
deps =
    pytest
    pytest-cov
```

```
[testenv:clean]
deps = coverage
skip_install = true
commands = coverage erase
```

For parallel runs we need to set some dependencies and have an extra report env like so:

```
[tox]
envlist = clean,py27,py36,report

[testenv]
commands = pytest --cov --cov-append --cov-report=term-missing
deps =
    pytest
    pytest-cov
depends =
    {py27,py36}: clean
    report: py27,py36

[testenv:report]
deps = coverage
skip_install = true
commands =
    coverage report
    coverage html

[testenv:clean]
deps = coverage
skip_install = true
commands = coverage erase
```

Depending on your project layout you might need extra configuration, see the working examples at <https://github.com/pytest-dev/pytest-cov/tree/master/examples> for two common layouts.

CHAPTER 8

Plugin coverage

Getting coverage on pytest plugins is a very particular situation. Because how pytest implements plugins (using setuptools entrypoints) it doesn't allow controlling the order in which the plugins load. See [pytest/issues/935](https://github.com/pytest-dev/pytest/issues/935) for technical details.

The current way of dealing with this problem is using the append feature and manually starting `pytest-cov`'s engine, eg:

```
COV_CORE_SOURCE=src COV_CORE_CONFIG=.coveragerc COV_CORE_DATAFILE=.coverage.eager
pytest -cov=src -cov-append
```

Alternatively you can have this in `tox.ini` (if you're using [Tox](#) of course):

```
[testenv]
setenv =
    COV_CORE_SOURCE=
    COV_CORE_CONFIG={toxindir}/.coveragerc
    COV_CORE_DATAFILE={toxindir}/.coverage
```

And in `pytest.ini` / `tox.ini` / `setup.cfg`:

```
[tool:pytest]
addopts = --cov --cov-append
```

Markers and fixtures

There are some builtin markers and fixtures in `pytest-cov`.

9.1 Markers

9.1.1 `no_cover`

Eg:

```
@pytest.mark.no_cover
def test_foobar():
    # do some stuff that needs coverage disabled
```

Warning: Caveat

Note that subprocess coverage will also be disabled.

9.2 Fixtures

9.2.1 `no_cover`

Eg:

```
def test_foobar(no_cover):
    # same as the marker ...
```

9.2.2 cov

For reasons that no one can remember there is a `cov` fixture that provides access to the underlying Coverage instance. Some say this is a disguised foot-gun and should be removed, and some think mysteries make life more interesting and it should be left alone.

10.1 2.7.0 (2019-05-03)

- Fixed `AttributeError: 'NoneType' object has no attribute 'configure_node'` error when `--no-cov` is used. Contributed by Alexander Shadchin in [#263](#).
- Various testing and CI improvements. Contributed by Daniel Hahler in [#255](#), [#266](#), [#272](#), [#271](#) and [#269](#).
- Improved documentation regarding subprocess and multiprocessing. Contributed in [#265](#).
- Improved `pytest_cov.embed.cleanup_on_sigterm` to be reentrant (signal deliveries while signal handling is running won't break stuff).
- Added `pytest_cov.embed.cleanup_on_signal` for customized cleanup.
- Improved cleanup code and fixed various issues with leftover data files. All contributed in [#265](#) or [#262](#).
- Improved examples. Now there are two examples for the common project layouts, complete with working coverage configuration. The examples have CI testing. Contributed in [#267](#).
- Improved help text for CLI options.

10.2 2.6.1 (2019-01-07)

- Added support for Pytest 4.1. Contributed by Daniel Hahler and in [#253](#) and [#230](#).
- Various test and docs fixes. Contributed by Daniel Hahler in [#224](#) and [#223](#).
- Fixed the “Module already imported” issue ([#211](#)). Contributed by Daniel Hahler in [#228](#).

10.3 2.6.0 (2018-09-03)

- Dropped support for Python < 3.4, Pytest < 3.5 and Coverage < 4.4.

- Fixed some documentation formatting. Contributed by Jean Jordaan and Julian.
- Added an example with `addopts` in documentation. Contributed by Samuel Giffard in [#195](#).
- Fixed `TypeError: 'NoneType' object is not iterable` in certain xdist configurations. Contributed by Jeremy Bowman in [#213](#).
- Added a `no_cover` marker and fixture. Fixes [#78](#).
- Fixed broken `no_cover` check when running doctests. Contributed by Terence Honles in [#200](#).
- Fixed various issues with path normalization in reports (when combining coverage data from parallel mode). Fixes [#130](#). Contributed by Ryan Hiebert & Ionel Cristian Mărieș in [#178](#).
- Report generation failures don't raise exceptions anymore. A warning will be logged instead. Fixes [#161](#).
- Fixed multiprocessing issue on Windows (empty env vars are not passed). Fixes [#165](#).

10.4 2.5.1 (2017-05-11)

- Fixed xdist breakage (regression in 2.5.0). Fixes [#157](#).
- Allow setting custom `data_file` name in `.coveragerc`. Fixes [#145](#). Contributed by Jannis Leidel & Ionel Cristian Mărieș in [#156](#).

10.5 2.5.0 (2017-05-09)

- Always show a summary when `--cov-fail-under` is used. Contributed by Francis Niu in [PR#141](#).
- Added `--cov-branch` option. Fixes [#85](#).
- Improve exception handling in subprocess setup. Fixes [#144](#).
- Fixed handling when `--cov` is used multiple times. Fixes [#151](#).

10.6 2.4.0 (2016-10-10)

- Added a “disarm” option: `--no-cov`. It will disable coverage measurements. Contributed by Zoltan Kozma in [PR#135](#).
- WARNING: Do not put this in your configuration files, it's meant to be an one-off for situations where you want to disable coverage from command line.**
- Fixed broken exception handling on `.pth` file. See [#136](#).

10.7 2.3.1 (2016-08-07)

- Fixed regression causing spurious errors when xdist was used. See [#124](#).
- Fixed `DeprecationWarning` about incorrect `addoption` use. Contributed by Florian Bruhin in [PR#127](#).
- Fixed deprecated use of `funcarg` fixture API. Contributed by Daniel Hahler in [PR#125](#).

10.8 2.3.0 (2016-07-05)

- Add support for specifying output location for html, xml, and annotate report. Contributed by Patrick Lannigan in [PR#113](#).
- Fix bug hiding test failure when cov-fail-under failed.
- For coverage ≥ 4.0 , match the default behaviour of *coverage report* and error if coverage fails to find the source instead of just printing a warning. Contributed by David Szotten in [PR#116](#).
- Fixed bug occurred when bare `--cov` parameter was used with xdist. Contributed by Michael Elovskikh in [PR#120](#).
- Add support for `skip_covered` and added `--cov-report=term-skip-covered` command line options. Contributed by Saurabh Kumar in [PR#115](#).

10.9 2.2.1 (2016-01-30)

- Fixed incorrect merging of coverage data when xdist was used and coverage was ≥ 4.0 .

10.10 2.2.0 (2015-10-04)

- Added support for changing working directory in tests. Previously changing working directory would disable coverage measurements in subprocesses.
- Fixed broken handling for `--cov-report=annotate`.

10.11 2.1.0 (2015-08-23)

- Added support for *coverage 4.0b2*.
- Added the `--cov-append` command line options. Contributed by Christian Ledermann in [PR#80](#).

10.12 2.0.0 (2015-07-28)

- Added `--cov-fail-under`, akin to the new `fail_under` option in *coverage-4.0* (automatically activated if there's a `[report] fail_under = ...` in `.coveragerc`).
- Changed `--cov-report=term` to automatically upgrade to `--cov-report=term-missing` if there's `[run] show_missing = True` in `.coveragerc`.
- Changed `--cov` so it can be used with no path argument (in which case the source settings from `.coveragerc` will be used instead).
- Fixed `.pth` installation to work in all cases (install, easy_install, wheels, develop etc).
- Fixed `.pth` uninstallation to work for wheel installs.
- Support for coverage 4.0.
- Data file suffixing changed to use coverage's `data_suffix=True` option (instead of the custom suffixing).
- Avoid warning about missing coverage data (just like `coverage.control.process_startup`).

- Fixed a race condition when running with xdist (all the workers tried to combine the files). It's possible that this issue is not present in *pytest-cov* 1.8.X.

10.13 1.8.2 (2014-11-06)

- N/A

CHAPTER 11

Authors

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- Rick van Hattem - <http://wol.ph>
- Buck Evan - <https://github.com/bukzor>
- Eric Larson - <http://larsoner.com>
- Marc Abramowitz - <http://marc-abramowitz.com>
- Thomas Kluyver - <https://github.com/takluyver>
- Guillaume Ayoub - <http://www.yabz.fr>
- Federico Ceratto - <http://firelet.net>
- Josh Kalderimis - <http://blog.cookiestack.com>
- Ionel Cristian Mărieș - <https://blog.ionelmc.ro>
- Christian Ledermann - <https://github.com/cleder>
- Alec Nikolas Reiter - <https://github.com/justanr>
- Patrick Lannigan - <https://github.com/plannigan>
- David Szotten - <https://github.com/davidszotten>
- Michael Elovskikh - <https://github.com/wronglink>
- Saurabh Kumar - <https://github.com/theskumar>
- Michael Elovskikh - <https://github.com/wronglink>
- Daniel Hahler - <https://daniel.hahler.de>
- Florian Bruhin - <http://www.the-compiler.org>
- Zoltan Kozma - <https://github.com/kozmaz87>
- Francis Niu - <https://fniu.github.io>
- Jannis Leidel - <https://github.com/jezdez>

- Ryan Hiebert - <http://ryanhiebert.com/>
- Terence Honles - <https://github.com/terencehonles>
- Jeremy Bowman - <https://github.com/jmbowman>
- Samuel Giffard - <https://github.com/Mulugruntz>
- - <https://github.com/MarSoft>
- Alexander Shadchin - <https://github.com/shadchin>

The process for releasing should follow these steps:

1. Test that docs build and render properly by running `tox -e docs,spell`.
If there are bogus spelling issues add the words in `spelling_wordlist.txt`.
2. Update `CHANGELOG.rst` and `AUTHORS.rst` to be up to date.
3. Bump the version by running `bumpversion [major | minor | patch]`. This will automatically add a tag.

Alternatively, you can manually edit the files and run `git tag v1.2.3` yourself.

4. Push changes and tags with:

```
git push
git push --tags
```

5. Wait for [AppVeyor](#) and [Travis](#) to give the green builds.
6. Check that the docs on [ReadTheDocs](#) are built.
7. Make sure you have a clean checkout, run `git status` to verify.
8. Manually clean temporary files (that are ignored and won't show up in `git status`):

```
rm -rf dist build src/*.egg-info
```

These files need to be removed to force `distutils/setuptools` to rebuild everything and recreate the `egg-info` metadata.

9. Build the dists:

```
python3.4 setup.py clean --all sdist bdist_wheel
```

10. Verify that the resulting archives (found in `dist/`) are good.
11. Upload the sdist and wheel with `twine`:

```
twine upload dist/*
```

Contributions are welcome, and they are greatly appreciated! Every little bit helps, and credit will always be given.

13.1 Bug reports

When [reporting a bug](#) please include:

- Your operating system name and version.
- Any details about your local setup that might be helpful in troubleshooting.
- Detailed steps to reproduce the bug.

13.2 Documentation improvements

pytest-cov could always use more documentation, whether as part of the official pytest-cov docs, in docstrings, or even on the web in blog posts, articles, and such.

13.3 Feature requests and feedback

The best way to send feedback is to file an issue at <https://github.com/pytest-dev/pytest-cov/issues>.

If you are proposing a feature:

- Explain in detail how it would work.
- Keep the scope as narrow as possible, to make it easier to implement.
- Remember that this is a volunteer-driven project, and that code contributions are welcome :)

13.4 Development

To set up *pytest-cov* for local development:

1. Fork *pytest-cov* (look for the “Fork” button).
2. Clone your fork locally:

```
git clone git@github.com:your_name_here/pytest-cov.git
```

3. Create a branch for local development:

```
git checkout -b name-of-your-bugfix-or-feature
```

Now you can make your changes locally.

4. When you’re done making changes, run all the checks, doc builder and spell checker with *tox* one command:

```
tox
```

5. Commit your changes and push your branch to GitHub:

```
git add .
git commit -m "Your detailed description of your changes."
git push origin name-of-your-bugfix-or-feature
```

6. Submit a pull request through the GitHub website.

13.4.1 Pull Request Guidelines

If you need some code review or feedback while you’re developing the code just make the pull request.

For merging, you should:

1. Include passing tests (run *tox*)¹.
2. Update documentation when there’s new API, functionality etc.
3. Add a note to *CHANGELOG.rst* about the changes.
4. Add yourself to *AUTHORS.rst*.

13.4.2 Tips

To run a subset of tests:

```
tox -e envname -- pytest -k test_myfeature
```

To run all the test environments in *parallel* (you need to `pip install detox`):

```
detox
```

¹ If you don’t have all the necessary python versions available locally you can rely on Travis - it will run the tests for each change you add in the pull request.
It will be slower though ...

CHAPTER 14

Indices and tables

- `genindex`
- `modindex`
- `search`